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AUTOMATED AERIAL REFUEL (AAR)
TECHNOLOGIES AND
CHALLENGES
Delivery Order 0048

David R. Riley

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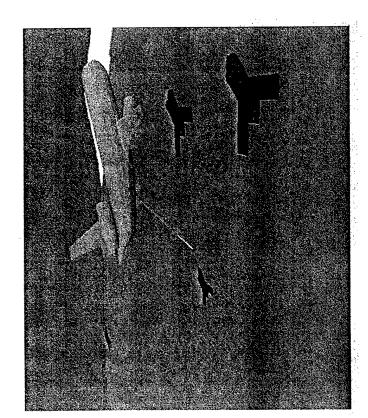
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Automated Aerial Refuel (AAR) **Technologies and Challenges**

AIAA Section Meeting 13 Apr 04



Video Courtesy Bihrle Applied Research



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Presentation Outline



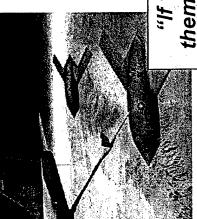
- Background
- Significance to Air Force
- AAR Program Key Aspects
- AAR Project Approach
- National AAR Team
- Conceptual Design Development Process
- AAR Process
- CONOPs and Requirements
- Conceptual Designs
- Selection Process
- Conceptual Design Families
- Simulation Development
- AAR's Future





Significance to Air Force

- Unmanned Aerial Vehicles
- Extends Range
- Shortens Response for Time-Critical Targets
- Maintains In-Theater Presence Using Fewer Assets
- Deployment with Manned Fighters and Attack Without the Need of Forward Staging Areas



"If we decided to fly them across the ocean, we have to work on things like automatic air refueling" -Gen. John Jumper, USAF, August

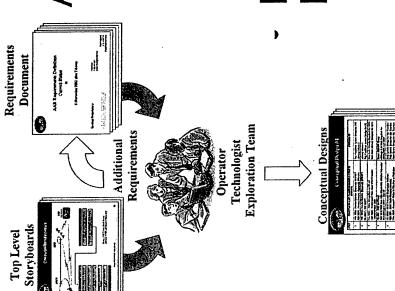
Manned Aircraft

- Provides Adverse Weather Operations
- Improves Fueling Efficiency
- Reduces Pilot Workload





AAR Program Key Aspects



Automating the Receiver

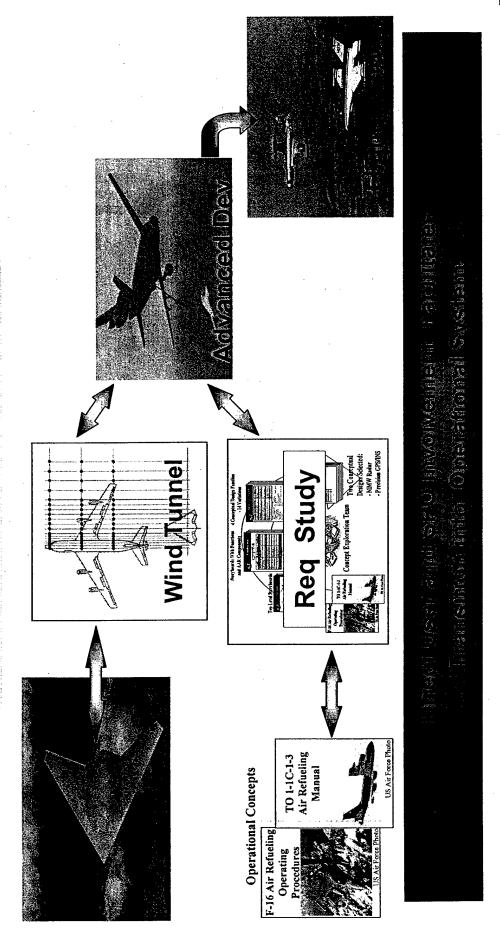
- Demonstrate an Operationally Feasible UAV Refueling Capability
- Near-Term Focus Boom/Receptacle Refueling
- Target was Air Force UAVs
- Near-Term Refueling

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AAR Project Approach

Heavy User Involvement From AMCIXPR; ACCIDRZ, ASC/FB, And DARPA





National AAR Team



ACC/DR



ASC/FB ASC/GR





AMC/XP

Navy

THE TORCE PROFACE ARON LABORATOR



NORTHROP GRUMMAN

Electronic Systems



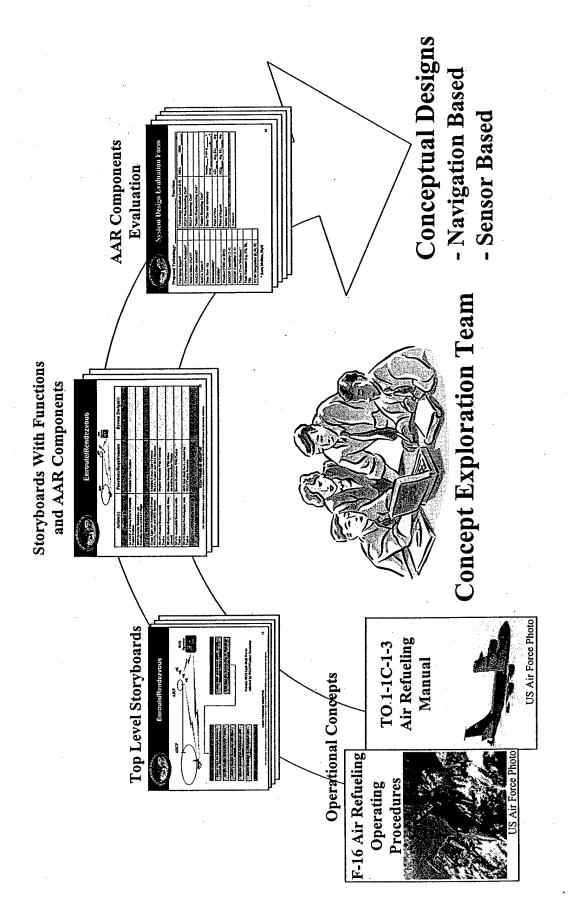






Conceptual Design Development Process

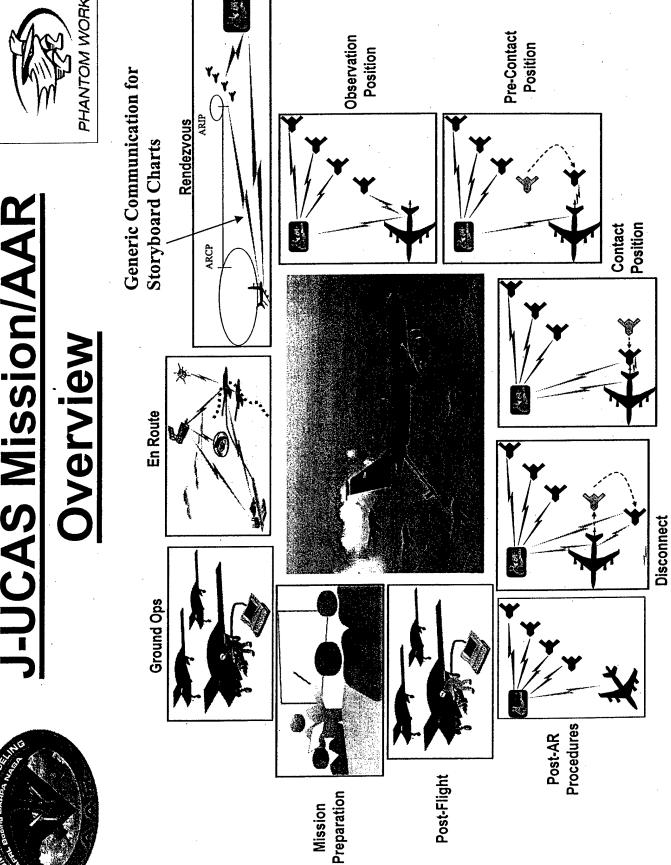






J-UCAS Mission/AAR

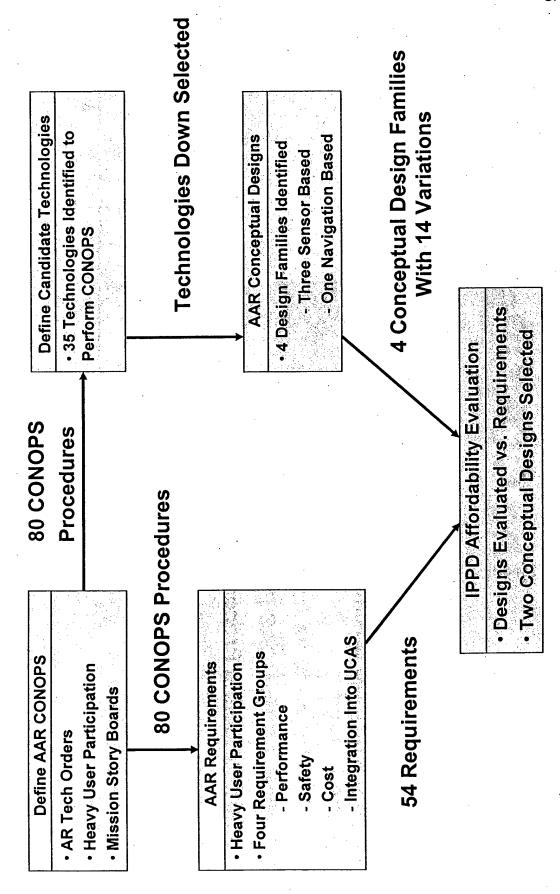






The AAR Process



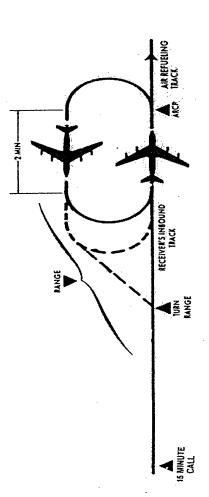




The CONOPs

- Working with ACC & AMC to Develop Conops
- Used F-16 Procedures As Baseline
- Refueling 4-Ship UCAS Packages
- Manned Refueling Procedures



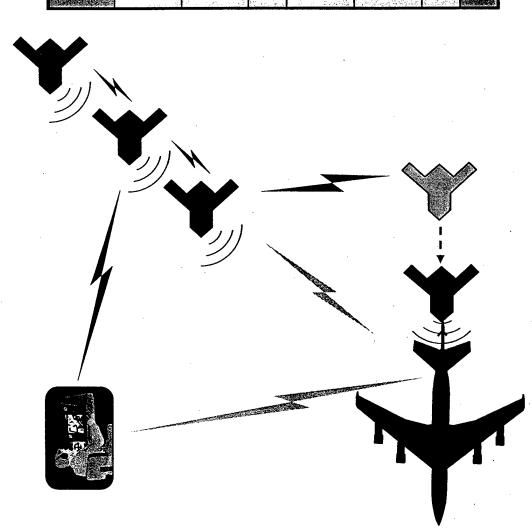


Based AAR Procedures On Current Manned Aircraft Procedure ट्रगडप्रातीगर्ध अभ्बत्माभिड्ड गिर्मंख्यांबार्गेला, ट्वडिंड गित्वापडांमंश्र



Example CONOPs: Contact Position





Authorized UCAS Stabilizes in Pre-Contact Position

Boomer Authorizes UCAS to Contact Position

Authorized UCAS Stabilizes in Contact Position

Boomer Plugs UCAS

UCAS Acknowledges Contact to MCS Operator

Confirmation of Contact Is Provided to Tanker UCAS Maintains Contact Position

UOAS Takes Fuel



Overarching User Requirements



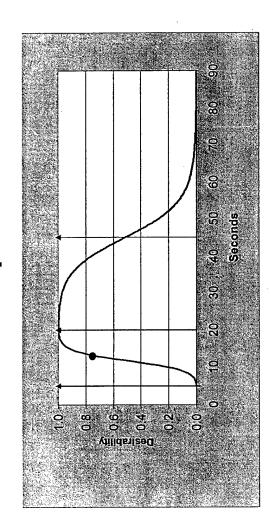
- User Relevance Requires:
- **Protect Tanker From Collision With UCASs**
- Identify and Design Most Affordable Solution
- Consider Impact to Rest of UCAS System of Systems (SoS) Impact
- Minimal Impact to LO Design
- Minimize (or Eliminate) Tanker Modifications
- Minimize Impact to Refueling Mixed Fleet Operation



AAR Requirements: Performance Example

POOTB: Refueling Efficiency: Closure to Contact

 UCAV will move smoothly and efficiently from the Precontact Position to the Contact Position upon Boomer authorization.



Time (seconds) from Boomer authorization (to close to contact) until receiver stabilizes in Contact Position.

Threshold is the typical time for piloted aircraft.

- 4 Areas

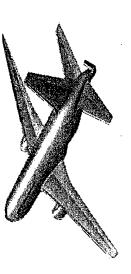
 Performance
- -Safety
 - -Cost
- -Integration
- 54 Requirements
- Developed With Direct Warfighter Involvement
- Derived from Battlefield Requirements and CONOPs



Conceptual Design Selection Critical Functions Drive AAR

- Strongest Design Drivers Functions (In Order of Priority):
- **UCAS Ability to Precisely Maneuver Around Tanker**
- **UCAS Ability to Perform Rendezvous with Tanker**
- Other Important Functions
- **Boomer Ability to Immediately Command Break-Away**
- Tanker's Ability to Determine Range to UCAS in Real **Fime (Point Parallel Rendezvous)**
- Tanker's Ability to Communicate with MCS Operator



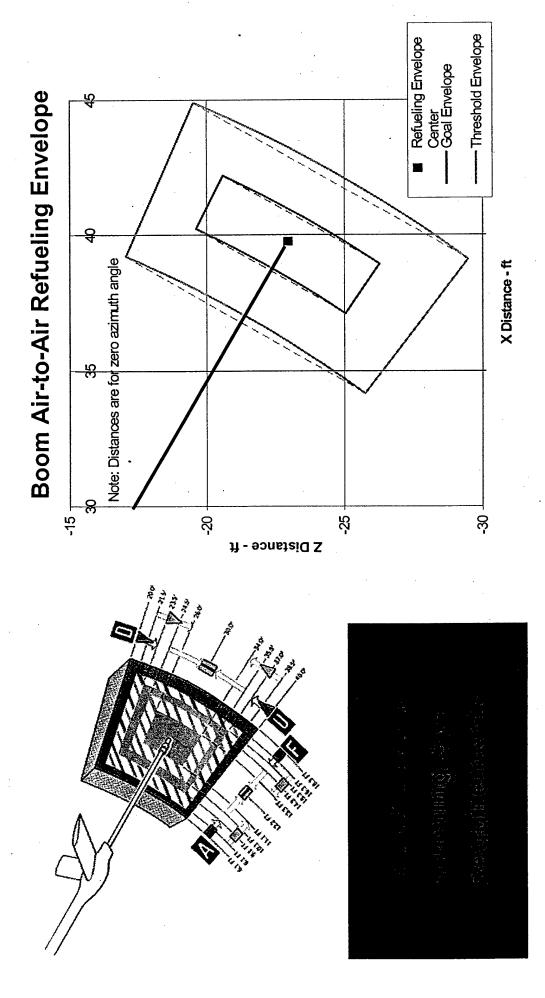




Precision Positioning System

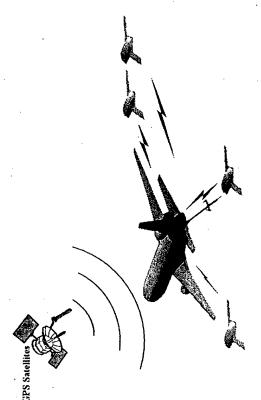








AAR Conceptual Design Families



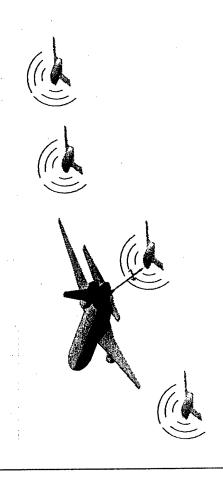
Navigation-Based

Advantages:

- Lowest Technical Risk For Initial Capability
- All Weather Capability
- Compatible With Navy Ops
 - Simple Vehicle Integration

Disadvantages:

Requires Tanker Modifications



Sensor Based

Advantages:

- Most Affordable Conceptual Design
- Sensor May Enable Additional UCAS Capabilities

Disadvantages:

- **UCAS Vehicle Integration**
- Sensor Development Risk



Simulation Development

- Integrated Aerial Refueling R&D Simulation **Being Developed**
- ▼ Boomer Station
- ∨ UCAS Operator Station
- ▼ Tanker Pilot Cube
- Provides Test Bed for AAR System Development
- Allows Rapid Prototyping and Early Operator Interactions
- ➤ Helps Develop and Visualize Correct Story Boards



Infinity Cube Simulation

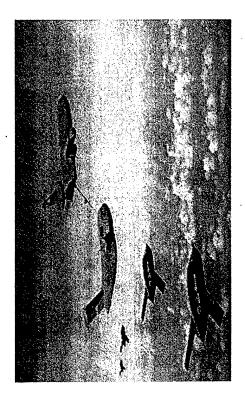




Summary



- Automated Refueling Is a Key Capability for UCAS
- Automation Can Provide Significant Improvements in Refueling Capability and Efficiency
- **Technology Application to Manned Aircraft**
- ▼ Automatic Adverse Weather Rendezvous
- Situational Awareness and Collision Avoidance for Simultaneous Multiple Receivers
- AFRL, ASC, AMC, ACC, and DARPA have Teamed With Industry
- Concepts Developed in Desktop Simulation Environment can be Quickly Moved to a Man-In-The-Loop Simulation Environment for Boomer, Tanker Pilot, and UAV Controller Evaluations





AAR's Future



Continue Requirements Development

- Analysis
- Simulation
- Off-Line Simulations
- Real Time "Boomer in the Loop"

AAR Technology Maturation

- Flight Test
- · Gather Sensor Data
- Demonstrate Station Keeping Capability
- Demonstrate Dry/Wet Hookups
- ▼ Boom and Receptacle
- **∀** Probe and Drogue

